



# Right-looking version of robust incomplete factorization preconditioner with pivoting

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## Abstract

In this paper, we use a complete pivoting strategy for the right-looking version of Robust Incomplete Factorization preconditioner and study effect of this pivoting.

**Keywords:** *ILU* factorization, right-looking version of *RIF* preconditioner, Krylov subspace methods.

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## 1 Introduction

Consider the linear system of equations of the form

$$Ax = b, \tag{1}$$

where the coefficient matrix  $A \in \mathbb{R}^{n \times n}$  is nonsingular, large, sparse and nonsymmetric and also  $x, b \in \mathbb{R}^n$ . Krylov subspace methods can be used to solve this system [5]. An implicit preconditioner  $M$  for system (1) is an approximation of matrix  $A$ , *i.e.*,  $M \approx A$ . If  $M$  is a good approximation of  $A$ , then it can be used as the right preconditioner for system (1). In this case, instead of solving system (1) it is better to solve the right preconditioned system  $AM^{-1}u = b$  where  $M^{-1}u = x$  by the Krylov subspace methods.

Suppose that there is the factorization  $A = LDU$  for matrix  $A$ ; where  $L$  and  $U^T$  are unit lower triangular matrices and  $D$  is a diagonal matrix. Also suppose that dropping be applied on  $L$ ,  $U$  and  $D$ . Then, matrix  $M$  which is  $A \approx M = LDU$  is an implicit preconditioner for system (1). This preconditioner is also termed as an *ILU* preconditioner.

In this paper, we present a complete pivoting strategy for right-looking version of *RIF* preconditioner. To test effectiveness of such a pivoting, we have generated several linear systems. The coefficient matrices are taken from University of Florida sparse matrix collection [4]. Then we have computed the right-looking version of *RIF* with pivoting for such systems and have solved the right preconditioned linear systems by the *GMRES*(30) Krylov subspace method [5].



## 2 Right-looking version of $RIF$ preconditioner with complete pivoting

An explicit preconditioner  $M$  for system (1) is an approximation of matrix  $A^{-1}$ , i.e.,  $M \approx A^{-1}$ . The most well-known explicit preconditioner is the  $AINV$  preconditioner [1]. This preconditioner has three factors in the form  $A^{-1} \approx M = ZD^{-1}W^T$  where  $Z$  and  $W$  are unit upper triangular matrices and  $D$  is a diagonal matrix. There are two left and right-looking versions for this preconditioner. In [3], Bollhoefer and Saad could present a complete pivoting strategy for the right-looking version of  $AINV$  preconditioner.

In 2003, Benzi and Tuma computed an incomplete factorization of a symmetric positive definite matrix  $A$  in the form of  $A \approx LDL^T$  as by-product of the  $AINV$  preconditioner. This preconditioner is termed Robust Incomplete Factorization or  $RIF$  [2]. There are also two left and right-looking versions for this preconditioner. In this paper, we focus on the nonsymmetric version of this preconditioner. The  $L$  and  $U$  factors of this preconditioner are computed independently. Algorithm 1, computes the right-looking version of this preconditioner and uses the complete pivoting strategy. At step  $i$  of Algorithm 1,  $i$ -th column of matrix  $L$  and  $i$ -th row of matrix  $U$  are computed, independently. More precisely, matrix  $L$  is computed column-wise and matrix  $U$  is computed row-wise. At the end of this algorithm, factorization  $\Pi A \Sigma \approx LDU$  is computed where  $\Pi$  and  $\Sigma$  are the row and column permutation matrices, respectively.

## 3 Numerical Results

In this section, we report results of  $GMRES(30)$  method to solve the original and the right preconditioned linear systems. Preconditioners are right-looking version of  $RIF$  with and without pivoting. We have used the notation  $RLRIF$  to indicate the right-looking version of  $RIF$  preconditioner in Tables 2 and 3. We have also considered the notation  $RLRIFP(1.0)$  in these tables to indicate the right-looking version of  $RIF$  with pivoting that uses parameter  $\alpha = 1.0$  for column and row pivoting. We have generated 8 artificial linear systems  $Ax = b$  with the nonsymmetric coefficient matrices from the University of Florida Sparse Matrix Collection [4]. Vector  $b$  is  $Ae$  in which  $e = [1, \dots, 1]^T$ . We have written code of right-looking version of  $RIF$  with pivoting in Fortran 90. We have selected  $\tau_l, \tau_u, \tau_w$  and  $\tau_z$  equal to 0.1.

In Table 1,  $n$  is the dimension and  $nnz$  is the number of nonzero entries of the matrix.  $it$  is the number of iterations of  $GMRES(30)$  method with no preconditioning and  $itime$  is its iteration time. This parameter is in seconds. A + means that there is no convergence in 5000 number of iterations. In Tables 1 and 3, convergence criterion is satisfied when the relative residual is less than  $10^{-10}$ .

In Table 2,  $Ptime$  is the preconditioning time and  $density = \frac{nnz(L)+nnz(U)}{nnz(A)}$ .  $Ptime$  is in seconds. For all matrices, the density of  $RLRIFP(1.0)$  and  $RLRIF$  preconditioners are so close to each other. This gives a proper atmosphere to compare number of iterations of  $GMRES(30)$ , when these two preconditioners are used as the right preconditioner. For matrix *orsirr\_2*,  $Ptime$  of  $RLRIFP(1.0)$  preconditioner is smaller than  $Ptime$  of  $RLRIF$  preconditioner. But for all other matrices,  $Ptime$  of  $RLRIFP(1.0)$  preconditioner is greater than or equal to  $Ptime$  of  $RLRIF$  preconditioner.




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### Algorithm 1 (Right-looking version of *RIF* with complete pivoting)

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Input:  $A = (a_{ij}) \in \mathbb{R}^{n \times n}$  and  $\tau_w, \tau_z \in (0, 1)$  be drop tolerances and prescribe a tolerance  $\alpha \in (0, 1]$ .

Output:  $\Pi A \Sigma \approx LDU$

1.  $\Pi = \Sigma = I_n$ .
2.  $w_i^{(0)} = e_i, z_i^{(0)} = e_i, 1 \leq i \leq n$ .
3. **for**  $i = 1$  to  $n$  **do**
4.    $m_i = n_i = 0$
5.    $satisfied\_p = false, satisfied\_q = false$ .
6.   **while** not  $satisfied\_p$  **do**
7.     **for**  $j = i$  to  $n$  **do**
8.        $p_j^{(i-1)} = (w_j^{(i-1)})^T (\Pi A \Sigma) z_i^{(i-1)}$ .
9.     **end for**
10.     **if**  $|p_i^{(i-1)}| < \alpha \max_{m \geq i} |p_m^{(i-1)}|$  **then**
11.        $m_i = m_i + 1, \pi_{m_i}^{(i-1)} = I_n$
12.        $satisfied\_q = false$ , choose  $k$  such that  $|p_k^{(i-1)}| = \max_{m \geq i} |p_m^{(i-1)}|$ .
13.       Interchange columns  $i$  and  $k$  of  $W - I$  and rows  $i$  and  $k$  of  $L - I$  and  $\pi_{m_i}^{(i-1)}$  and elements  $p_i^{(i-1)}$  and  $p_k^{(i-1)}$ .
14.        $\Pi = \pi_{m_i}^{(i-1)} \Pi$
15.     **end if**
16.      $satisfied\_p = true$
17.     **for**  $j = i$  to  $n$  **do**
18.        $q_j^{(i-1)} = (z_j^{(i-1)})^T (\Pi A \Sigma)^T w_i^{(i-1)}$ .
19.     **end for**
20.     **if** not  $satisfied\_q$  **then**
21.       **if**  $|q_i^{(i-1)}| < \alpha \max_{m \geq i} |q_m^{(i-1)}|$  **then**
22.           $n_i = n_i + 1, \sigma_{n_i}^{(i-1)} = I_n$
23.           $satisfied\_p = false$ , choose  $l$  such that  $|q_l^{(i-1)}| = \max_{m \geq i} |q_m^{(i-1)}|$ .
24.          Interchange columns  $i$  and  $l$  of  $Z - I, U - I$  and  $\sigma_{n_i}^{(i-1)}$  and elements  $q_i^{(i-1)}$  and  $q_l^{(i-1)}$ .
25.           $\Sigma = \Sigma \sigma_{n_i}^{(i-1)}$
26.       **end if**
27.       **end if**
28.        $satisfied\_q = true$ .
29.     **end while**
30.      $d_{ii} = p_i^{(i-1)}$ .
31.     **for**  $j = i + 1$  to  $n$  **do**
32.        $p_j^{(i-1)} = \frac{p_j^{(i-1)}}{d_{ii}}, q_j^{(i-1)} = \frac{q_j^{(i-1)}}{d_{ii}}$ .
33.        $L_{ji} = p_j^{(i-1)}, U_{ij} = q_j^{(i-1)}$ .
34.       apply dropping rule to  $L_{ji}$  and to  $U_{ij}$  if their absolute values are less than  $\tau_l$  and  $\tau_u$ .
35.        $w_j^{(i)} = w_j^{(i-1)} - p_j^{(i-1)} w_i^{(i-1)}, z_j^{(i)} = z_j^{(i-1)} - q_j^{(i-1)} z_i^{(i-1)}$ .
36.       for all  $l \leq i$  apply a dropping rule to  $w_{lj}^{(i)}$  and to  $z_{lj}^{(i)}$ , if their absolute values are less than  $\tau_w$  and  $\tau_z$ .
37.     **end for**
38. **end for**
39. Return  $L = (L_{ij})_{1 \leq i, j \leq n}, U = (U_{ij})_{1 \leq i, j \leq n}, D = diag(d_{ii})_{1 \leq i \leq n}, \Pi$  and  $\Sigma$

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In Table 3, results of *GMRES*(30) method are presented. In this table, *it* is again the number of iterations of this Krylov subspace method and *Ttime* is its total time which is defined as the iteration time plus the preconditioning time. Comparing columns 2 and 4 of this table, indicates that except for matrix *raefsky6*, the number of iterations of *GMRES*(30), when one uses the *RLRIFP*(1.0) preconditioner, is less than or equal to the number of iterations of this Krylov subspace method when one applies the *RLRIF* preconditioner. Columns 3 and 5 of this table, indicate that for 6 matrices *Ttime* of *RLRIFP*(1.0) preconditioner is less than *Ttime* of *RLRIF* preconditioner and for 2 other matrices this is vice versa. Comparing column 2 of Table 3 with column 4 of Table 1, shows that *RLRIFP*(1.0) preconditioner is useful to decrease the number of iterations of *GMRES*(30) method.



## 4 Conclusion

In this paper, we presented right-looking version of *RIF* preconditioner with pivoting. We used parameter  $\alpha = 1.0$  to compute this preconditioner. We also used this preconditioner as the right preconditioner to solve several linear systems. Numerical experiments indicate the fact that, although *Ptime* of right-looking version of *RIF* preconditioner with pivoting for most of the tests is greater than *Ptime* of right-looking version of *RIF* preconditioner, but the right-looking version of *RIF* with pivoting is more effective than right-looking version of *RIF* to decrease the number of iterations of *GMRES*(30) method.

Table 1: matrix properties and results of *GMRES*(30) with no preconditioning.

Matrix	<i>n</i>	<i>nnz</i>	<i>It</i>	<i>Itime</i>
<i>add20</i>	2395	17319	1022	0.7500
<i>raefsky1</i>	3242	294276	+	+
<i>raefsky2</i>	3242	294276	+	+
<i>raefsky5</i>	6316	168658	+	+
<i>raefsky6</i>	3402	137845	+	+
<i>sherman4</i>	1104	3786	722	0.2188
<i>orsirr_1</i>	1030	6858	+	+
<i>orsirr_2</i>	886	5970	+	+

Table 2: properties of *RLRIFP*(1.0) and *RLRIF* preconditioners.

method	<i>RLRIFP</i> (1.0)		<i>RLRIF</i>	
	<i>Ptime</i>	<i>density</i>	<i>Ptime</i>	<i>density</i>
<i>add20</i>	0.0468	0.5556	0.0312	0.5354
<i>raefsky1</i>	0.2187	0.0895	0.0781	0.0911
<i>raefsky2</i>	0.3125	0.1458	0.1094	0.1473
<i>raefsky5</i>	0.1093	0.2526	0.0625	0.2602
<i>raefsky6</i>	0.0781	0.0872	0.0781	0.2739
<i>sherman4</i>	0.0156	1.2556	0.0156	1.2361
<i>orsirr_1</i>	0.0312	0.6211	0.0156	0.5426
<i>orsirr_2</i>	0.0312	0.6229	0.0313	0.5457

Table 3: results of *GMRES*(30) using *RLRIFP*(1.0) and *RLRIF* preconditioners

method	<i>RLRIFP</i> (1.0)		<i>RLRIF</i>	
	<i>it</i>	<i>Ttime</i>	<i>it</i>	<i>Ttime</i>
<i>add20</i>	15	0.0468	21	0.0469
<i>raefsky1</i>	642	2.4218	814	2.8281
<i>raefsky2</i>	636	2.5937	738	2.7188
<i>raefsky5</i>	10	0.1250	10	0.0938
<i>raefsky6</i>	10	0.0937	9	0.0938
<i>sherman4</i>	61	0.0625	69	0.0313
<i>orsirr_1</i>	49	0.0468	106	0.0469
<i>orsirr_2</i>	49	0.0312	105	0.0625

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